

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	311	(detect\$6 or captur\$4 or scan\$6 or read\$4)same(document\$6 near10 edg\$4)same(background\$3)	US-PGPUB; USPAT	OR	ON	2006/01/05 12:56
S2	4186	(detect\$6 or captur\$4 or scan\$6 or read\$4)same(document\$6)same(background\$3)	US-PGPUB; USPAT	OR	ON	2006/01/05 12:56
S3	586	S2 same(orientation\$4 or rotat\$6 or mov\$3 or shift\$3)	US-PGPUB; USPAT	OR	ON	2006/01/05 13:56
S4	192	S3 same(divid\$3 or segment\$6 or portion\$3 or partial\$3 or region\$3 or partition\$3)	US-PGPUB; USPAT	OR	ON	2006/01/05 13:57
S5	35	S4 same (edg\$4)	US-PGPUB; USPAT	OR	ON	2006/01/05 13:58
S6	1	"5377019".PN.	USPAT; USOCR	OR	ON	2006/01/05 13:52
S7	1	"5260804".PN.	USPAT; USOCR	OR	ON	2006/01/05 13:54
S8	1	"5377019".PN.	USPAT; USOCR	OR	ON	2006/01/05 13:54
S9	631	S2 same(orientation\$4 or rotat\$6 or mov\$3 or shift\$3 or skew\$3)	US-PGPUB; USPAT	OR	ON	2006/01/05 13:56
S10	210	S3 same(divid\$3 or segment\$6 or portion\$3 or partial\$3 or region\$3 or partition\$3 or sampl\$4)	US-PGPUB; USPAT	OR	ON	2006/01/05 13:57
S11	36	S10 same (edg\$4)	US-PGPUB; USPAT	OR	ON	2006/01/06 07:30
S12	1	"6198845".PN.	USPAT; USOCR	OR	ON	2006/01/05 13:59
S13	1	"5881166".PN.	USPAT; USOCR	OR	ON	2006/01/05 13:59
S14	1	"5848183".PN.	USPAT; USOCR	OR	ON	2006/01/05 13:59
S15	1	"5835628".PN.	USPAT; USOCR	OR	ON	2006/01/05 14:00
S16	1	"5832105".PN.	USPAT; USOCR	OR	ON	2006/01/05 14:00
S17	1	"5751848".PN.	USPAT; USOCR	OR	ON	2006/01/05 14:00
S18	455235	"11" same (rotat\$6)	US-PGPUB; USPAT	OR	ON	2006/01/06 06:25
S19	4186	(detect\$6 or captur\$4 or scan\$6 or read\$4)same(document\$6)same(background\$3)	US-PGPUB; USPAT	OR	ON	2006/01/06 06:31

S20	586	S19 same(orientation\$4 or rotat\$6 or mov\$3 or shift\$3)	US-PGPUB; USPAT	OR	ON	2006/01/06 06:25
S21	210	S20 same(divid\$3 or segment\$6 or portion\$3 or partial\$3 or region\$3 or partition\$3 or sampl\$4)	US-PGPUB; USPAT	OR	ON	2006/01/06 06:25
S22	36	S21 same (edg\$4)	US-PGPUB; USPAT	OR	ON	2006/01/06 06:26
S23	40	S21 same (rotat\$6)	US-PGPUB; USPAT	OR	ON	2006/01/06 06:26
S24	6	S23 same (edg\$4)	US-PGPUB; USPAT	OR	ON	2006/01/06 06:33
S25	120	(rotat\$6)same(detect\$6 or captur\$4 or scan\$6 or read\$4)same(document\$6)same(background\$3)	US-PGPUB; USPAT	OR	ON	2006/01/06 06:27
S26	10	S25 same (edg\$4)	US-PGPUB; USPAT	OR	ON	2006/01/06 07:32
S27	39	(detect\$6 or captur\$4 or scan\$6 or read\$4)same(document\$6 near10 rotat\$6)same(background\$3)	US-PGPUB; USPAT	OR	ON	2006/01/06 06:32
S28	76	(detect\$6 or captur\$4 or scan\$6 or read\$4)same(document\$6 near10(skew\$3 or rotat\$6))same(background\$3)	US-PGPUB; USPAT	OR	ON	2006/01/06 06:33
S29	33	S28 same (edg\$4)	US-PGPUB; USPAT	OR	ON	2006/01/06 06:33
S30	0	S25 same ((camera\$3 or sensor\$2)near10 digit\$6)	US-PGPUB; USPAT	OR	ON	2006/01/06 07:31
S31	4	S21 same ((camera\$3 or sensor\$2)near10 digit\$6)	US-PGPUB; USPAT	OR	ON	2006/01/06 07:31
S32	97	S19 same ((camera\$3 or sensor\$2)near10 digit\$6)	US-PGPUB; USPAT	OR	ON	2006/01/06 07:31
S33	44	S32 same (edg\$4)	US-PGPUB; USPAT	OR	ON	2006/01/06 07:32
S34	1	("5842194").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/01/27 06:27
S35	2321	((invers\$6 or revers\$6)near10 video\$2)same(fac\$2 or medical\$3 or human\$3 or operator\$3 or customer\$2 or user\$2 or viewer\$3 or driver\$2)	US-PGPUB; USPAT	OR	ON	2006/01/27 07:59
S36	1466	S35 same display\$4	US-PGPUB; USPAT	OR	ON	2006/01/27 08:00
S37	158	S36 same (nois\$2 or eye\$3 or mous\$3)	US-PGPUB; USPAT	OR	ON	2006/01/27 07:24

S38	17	S37 same(stor\$4 or memor\$4 or databas\$3)	US-PGPUB; USPAT	OR	ON	2006/01/27 07:24
S39	153	S36 same (nos\$2 or eye\$3 or mous\$3)	US-PGPUB; USPAT	OR	ON	2006/01/27 07:24
S40	63	S36 same (nos\$2 or eye\$3 or head\$1)	US-PGPUB; USPAT	OR	ON	2006/01/27 07:25
S41	5	S40 same(stor\$4 or memor\$4 or databas\$3)	US-PGPUB; USPAT	OR	ON	2006/01/27 07:24
S42	691	((invers\$6 or revers\$6)near10 video\$2)same(fac\$4 or human\$3 or operator\$3 or custmer\$2 or user\$2 or viewer\$3 or driver\$2)same(scan\$4 or read\$4 or captur\$4 or detect\$3)	US-PGPUB; USPAT	OR	ON	2006/01/27 08:04
S43	422	S42 same display\$4	US-PGPUB; USPAT	OR	ON	2006/01/27 08:01
S44	88	S42 same digit\$4	US-PGPUB; USPAT	OR	ON	2006/01/27 08:01
S45	61	S43 same digit\$4	US-PGPUB; USPAT	OR	ON	2006/01/27 08:01
S46	17	((invers\$6 or revers\$6)near10 video\$2)same(fac\$4 near10(human\$3 or operator\$3 or custmer\$2 or user\$2 or viewer\$3 or driver\$2))same(scan\$4 or read\$4 or captur\$4 or detect\$3)	US-PGPUB; USPAT	OR	ON	2006/01/27 08:07
S47	3	((invers\$6 or revers\$6)near10 video\$2)same((faces or face or factial\$3) near10(human\$3 or operator\$3 or custmer\$2 or user\$2 or viewer\$3 or driver\$2))same(scan\$4 or read\$4 or captur\$4 or detect\$3)	US-PGPUB; USPAT	OR	ON	2006/01/27 08:08
S48	12	((playback\$3 or play-back\$4 or invers\$6 or revers\$6)near10 video\$2)same((faces or face or factial\$3) near10(human\$3 or operator\$3 or custmer\$2 or user\$2 or viewer\$3 or driver\$2))same(scan\$4 or read\$4 or captur\$4 or detect\$3)	US-PGPUB; USPAT	OR	ON	2006/01/27 10:22
S49	0	("JP-10334213-\$.did.").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/01/27 10:25
S50	0	("JP-334213-\$.did.").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/01/27 10:26
S51	0	("JP-1998334213-\$.did.").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/01/27 10:28

S52	0	("JP-98334213-\$.did.").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/01/27 10:29
S53	0	("JP-9810-334213-\$.did.").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/01/27 10:29
S54	0	("JP-9810334213-\$.did.").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/01/27 10:29
S55	0	("JP-98-10334213-\$.did.").PN.	US-PGPUB; USPAT; USOCR; JPO	OR	OFF	2006/01/27 10:34
S56	0	(JP-98-10/334213-\$.did.).CCLS.	US-PGPUB; USPAT; USOCR; JPO	OR	OFF	2006/01/27 10:34
S57	0	(JP-9810/334213-\$.did.).CCLS.	US-PGPUB; USPAT; USOCR; JPO	OR	OFF	2006/01/27 14:07
S58	1	("6035074").PN.	US-PGPUB; USPAT; USOCR; JPO	OR	OFF	2006/01/27 15:00
S59	0	hiroyuki near2 fujimoto	US-PGPUB; USPAT	OR	ON	2006/01/27 15:01
S60	47	hiroyuki near2 fujimoto	US-PGPUB; USPAT	OR	ON	2006/01/27 15:11
S61	0	S60 same video\$2 near4 invers\$4	US-PGPUB; USPAT	OR	ON	2006/01/27 15:03
S62	0	S60 same video\$2 near4 (revers\$3 or invers\$4)	US-PGPUB; USPAT	OR	ON	2006/01/27 15:02
S63	0	S60 same video\$2	US-PGPUB; USPAT	OR	ON	2006/01/27 15:02
S64	0	S60 and video\$2 near4 invers\$4	US-PGPUB; USPAT	OR	ON	2006/01/27 15:03
S65	0	S60 and (video\$2 near4 invers\$4)	US-PGPUB; USPAT	OR	ON	2006/01/27 15:03
S66	0	kugimiya near2 hidezo	US-PGPUB; USPAT	OR	ON	2006/02/01 15:57
S67	1	("6699927").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/02/01 16:10

S68	4990	(camera\$2 or scanner\$3 or reader\$3 or imager\$3)same(adjust\$4 or correct\$3 or enhanc\$6)same(position\$4 or orthogon\$6 or mov\$6)same(tabl\$3 or stag\$3)	US-PGPUB; USPAT	OR	ON	2006/02/01 16:14
S69	128	S68 same((compensat\$6 or calibration\$3)near10 camera\$2)	US-PGPUB; USPAT	OR	ON	2006/02/01 16:16
S70	83	S69 same imag\$3	US-PGPUB; USPAT	OR	ON	2006/02/01 16:16
S71	1	"6028672".PN.	USPAT; USOCR	OR	ON	2006/02/01 16:18
S72	1	"5747822".PN.	USPAT; USOCR	OR	ON	2006/02/01 16:18
S73	1	"5142357".PN.	USPAT; USOCR	OR	ON	2006/02/01 16:18
S74	1	"5528290".PN.	USPAT; USOCR	OR	ON	2006/02/01 17:27


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Key: IEEE JNL = IEEE Journal or Magazine, IEEE JNL = IEEE Journal or Magazine, IEEE CNF = IEEE Conference, IEEE CNF = IEEE Conference, IEEE STD = IEEE Standard

1. **Step-and-shoot versus continuous helical pinhole SPECT for improved axial resolution**
 Patil, N.H.; Metzler, S.D.;
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2. **A multi-camera conical imaging system for robust 3D motion estimation, positioning and mapping from UA**
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3. **A self-calibration technique for active vision systems**
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4. **Robust vision-based pose control**
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5. **Robust visual servoing based on relative orientation**
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7. **Fast object segmentation from a moving camera**
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8. **Infrared Polarimetric Camera development**
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9. **Analysis of camera movement errors in vision-based vehicle tracking**
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10. **The active recovery of 3D motion trajectories and their use in prediction**
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11. **Two-stage motion compensation using adaptive global MC and local affine MC**
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12. **A multi-stage classifier based algorithm of pedestrian detection in night with a near infrared camera in a moving car**
Hui Sun; Chengying Hua; Yupin Luo;
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13. **Visual odometry**
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14. **Multi-camera conical imaging; calibration and robust 3-D motion estimation for ROV based mapping and positioning**
Firoozfam, P.; Shahriar Negahdaripour;
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15. **Underwater mosaicing and trajectory reconstruction using global alignment**
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- 18. Shape from video**
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- 19. Omni-Rig sensors: what can be done with a non-rigid vision platform?**
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- 20. Depth recovery using active focus in robotics [vision]**
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- 22. A new identification Jacobian for robotic hand/eye calibration**
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- 23. Epipolar geometry from profiles under circular motion**
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- 24. Sensor integration in airborne mapping**
Toth, C.K.;
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- 25. Learning and synthesizing MPEG-4 compatible 3-D face animation from video sequence**
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Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	1	(sequenc\$3 and collect\$4 and calibrat\$6 and position\$4 and orthogonal\$4 and error\$2).clm.	US-PGPUB	OR	ON	2006/02/02 17:17